

# The Monte Carlo method for conjugate stationary diffusion equation with special item\*

A.V. Burmistrov

## 1. The basic estimator

Consider the three-dimensional Dirichlet problem for the equation

$$\Delta u + (v, \text{grad } u) + cu = -g, \quad u|_{\Gamma} = \psi \quad (1.1)$$

in a domain  $\Omega$  with the boundary  $\Gamma$ , which is assumed simply connected and piecewise smooth. We suppose the functions  $v$ ,  $c$ , and  $g$  to satisfy the Hölder condition in  $\bar{\Omega}$ , and the function  $\psi$  to be continuous on  $\Gamma$ . Let  $\Gamma_{\varepsilon}$  be  $\varepsilon$ -neighborhood of  $\Gamma$ , let  $D(r)$  be the maximal ball with center at the point  $r$ , which lies in  $\bar{\Omega}$ , and let  $S(r)$  be the corresponding sphere of the radius  $d = d(r)$ . For the function  $u(r)$  we can write down the corresponding integral equation which has the following form in  $\Omega \setminus \Gamma_{\varepsilon}$  [2]:

$$\begin{aligned} u_1(r) = & \frac{1}{4\pi d^2(r)} \int_{S(r)} u_1(r'(s)) ds + \int_{D(r)} G_r(r') c(r') u_1(r') dr' + \\ & \int_{D(r)} G_r(r') (v(r'), \text{grad } u_1(r')) dr' + \int_{D(r)} G_r(r') g(r') dr'. \end{aligned} \quad (1.2)$$

Where

$$G_r(r') = \frac{1}{4\pi} \left( \frac{1}{|r - r'|} - \frac{1}{d} \right)$$

is the “central” Green’s function for the ball  $D(r)$ . We consider  $u_1 \equiv u$  for  $r \in \Gamma_{\varepsilon}$ . Denote the unit vector in the direction of the velocity  $v$  by  $l$ , i.e.,  $l = v/|v|$ . Using “non-central” Green’s function we can derive the following integral equation for the function  $(\text{grad } u_1(r))_l \equiv \partial u_1 / \partial l$  (see, e.g. [2]):

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$$\begin{aligned} \frac{\partial u_1}{\partial l}(r) = & \int_{S(r)} \frac{3a_l(r, r'(s))u_1(r'(s))}{4\pi d^3(r)} ds + \int_{D(r)} \frac{\partial G_l}{\partial l}(r, r')c(r')u_1(r') dr' + \\ & \int_{D(r)} \frac{\partial G_l}{\partial l}(r, r')(v(r'), \text{grad } u_1(r')) dr' + \int_{D(r)} \frac{\partial G_l}{\partial l}(r, r')g(r') dr'. \end{aligned} \quad (1.3)$$

Where  $a_l(r, r') = (r' - r, l)/|r' - r|$  is the cosine of the angle between unit vector  $l$  and the vector  $r' - r$ . Note that the functions

$$F_0(r, r') = \frac{6G_r(r')}{d^2(r)} \quad \text{and} \quad F(r, r') = \frac{4}{3d(r)a_l} \frac{\partial G_l}{\partial l}(r, r') = \frac{d^3 - |r - r'|^3}{3\pi d^4 |r - r'|^2}$$

are probability densities in the ball  $D(r)$ . To construct the algorithms of the Monte Carlo method, we henceforth combine (1.2) and (1.3) into a single integro-algebraic equation by means of a special extension of the phase space. Here it is reasonable to consider  $(v, \text{grad } u)$  in the moving coordinate system with the basis vector  $l(r) = v(r)/|v(r)|$ , in this system  $(v, \text{grad } u) = v \cdot \frac{\partial u}{\partial l}$ . Moreover, we pass from the function  $\frac{\partial u}{\partial l}(r)$  to the function  $\frac{d(r)}{3} \frac{\partial u}{\partial l}(r)$ .

Extend the phase space by adding a discrete variable  $j$ :  $j = 0$  or  $j = 1$ . Put  $w = (r, j)$  and introduce the following notations:

$$\begin{aligned} U(w) = U(r, j) = & \begin{cases} u(r), & j = 0, \\ \frac{d(r)}{3} \frac{\partial u}{\partial l}(r), & j = 1, \end{cases} \quad k(w, w') = \begin{cases} \frac{F_0(r, r')}{2}, & j = 0, \\ \frac{F(r, r')}{2}, & j = 1, \end{cases} \\ H(w) = & \begin{cases} \int_{D(r)} G_r(r')g(r') dr', & j = 0, \\ \frac{d(r)}{3} \int_{D(r)} \frac{\partial G_l}{\partial l}(r, r')g(r') dr', & j = 1, \end{cases} \quad a(w, w') = \begin{cases} 1, & j = 0, \\ a_l(r, r'), & j = 1, \end{cases} \\ M(w, w') = & \begin{cases} \frac{2c(r')}{c_0}, & j = 0, \quad j' = 0, \\ \frac{6v(r')}{c_0 d(r')}, & j = 0, \quad j' = 1, \\ \frac{3c(r')a_l(r, r')}{c_0}, & j = 1, \quad j' = 0, \\ \frac{9v(r')a_l(r, r')}{c_0 d(r')}, & j = 1, \quad j' = 1. \end{cases} \end{aligned} \quad (1.4)$$

Here  $c_0$  is a constant satisfying the inequality  $c_0 d_{\max}^2 < 6$ . Using these notations, write down the system of integral equations (1.2), (1.3) in the form

$$U_1(w) = H(w) + \left[1 - \frac{c_0 d^2(r)}{6}\right] \int_{S(r)} \frac{a(w, r'(s), 0)}{1 - c_0 d^2/6} \frac{U_1(r'(s), 0)}{4\pi d^2(r)} ds +$$

$$\left[\frac{c_0 d^2(r)}{6}\right] \sum_{j'=0}^1 \int_{D(r)} M(w, w') k(w, w') U_1(w') dr', \quad r \in \Omega \setminus \Gamma_\varepsilon, \quad (1.5)$$

$$U_1(w) \equiv U(w), \quad r \in \Gamma_\varepsilon.$$

According to (1.5), the estimator of the Monte Carlo method for  $U(w)$  is constructed as follows.

With the probability  $1 - c_0 d^2(r_n)/6$ , the new point  $r_{n+1}$  is chosen uniformly at random on the sphere  $S(r_n)$ , the weight  $Q_n$  is multiplied by  $[1 - c_0 d^2(r_n)/6]^{-1} a(w_n, w_{n+1})$ , and  $j_{n+1}$  is set to equal 0.

With the probability  $c_0 d^2(r_n)/6$  the point  $r_{n+1}$  is chosen at random in the ball  $D(r_n)$  with the density  $2k(w_n, w')$ . Next,  $j_{n+1}$  takes one of the values 0 or 1 with equal probabilities. Finally, the weight  $Q_n$  is multiplied by  $M(w_n, w_{n+1})$ .

In the process of modeling, this "walk on spheres and balls", when the point occurs in  $\Gamma_\varepsilon$  at a random step  $N$ , the chain terminates and the estimator of solution, multiplied by the weight, is added to the counter. As a result we obtain the following estimator for  $U(w_0)$ :

$$\xi(w_0) = \sum_{n=0}^N Q_n H(w_n),$$

where

$$Q_n = \prod_{i=1}^{m_n} M(w_{k_i-1}, w_{k_i}) \prod_{i=1}^{n-m_n} \frac{a(w_{t_i-1}, w_{t_i})}{1 - c_0 d^2(r_{t_i-1})/6}.$$

Here  $\{r_{t_i}\}$ ,  $i = 1, \dots, n - m_n$ , are points chosen on spheres, and  $\{r_{k_i}\}$ ,  $i = 1, \dots, m_n$ , are points chosen in balls. The function  $H(w) = H(r, j) = h_j(r)$  can be estimated by the Monte Carlo method for one "random knot" [1].

## 2. Unbiasedness of the estimator and boundedness of the variance

**Lemma 1.** *Suppose that the conditions*

$$|c(r)| \leq \frac{c_0}{3}, \quad |v| \leq \frac{c_0}{9} d(r), \quad (2.1)$$

*are satisfied for  $c_0 < 6c^*/\pi^2$ , where  $-c^*$  is the first eigenvalue of the Laplace operator in  $\Omega$ . Then the Neumann series for equation (1.5) converges.*

**Proof.** Consider the function

$$f(x) = \frac{6}{x^2} \left( 1 - \frac{\sin x}{x} \right) = 1 - \frac{6}{5!}x^2 + \frac{6}{7!}x^4 - \frac{6}{9!}x^6 + \dots$$

It is easy to see that the function  $f(x)$  decreases from 1 to  $6/\pi^2$  on the interval  $[0, \pi]$ . On the other hand, the inequality  $c_0/c^* < f(x)$  implies that

$$\frac{1}{1 - c_0 d_i^2/6} < \frac{d_i \sqrt{c^*}}{\sin d_i \sqrt{c^*}}, \quad (2.2)$$

where

$$x = d_i \sqrt{c^*} \leq d_{\max} \sqrt{c^*} \leq \pi.$$

In view of (2.1), relation (2.2) means that  $\xi(w_0)$  termwise dominated by some (not necessarily maximal) standard estimator  $\zeta$  of a "walk on spheres" for which the Neumann series converges [2].  $\square$

For specific types of domains, the condition  $c_0/c^* < 6/\pi^2 \approx 0.6079$  can be weakened on accounting for the exact value of  $d_{\max}$ . For example, for a cube with the edge  $b$  we have  $c^* = 3\pi^2/b^2$ ,  $d_{\max} = b/2$ ,  $c_0/c^* \leq 0.6888$ .

**Lemma 2.** Let  $U_0$  and  $K_0$  be respectively the Neumann series and the integral operator of equation (1.5) for  $a_l \equiv 1$ ,  $c \equiv c_0/3$ ,  $0 < c_0 < 6c^*/\pi^2$ ,  $g \equiv g_0 > 0$ , and  $v_0(r) = \frac{c_0 d(r)}{9} \frac{v}{|v|} \operatorname{sgn} U_0(r, 1)$ . Moreover, assume be satisfied the following conditions in  $\Gamma_\varepsilon$ :  $U_0(r, 1) = C^0$  and  $U_0(r, 0) = u_0$ , where

$$\Delta u_0 + c u_0 = -g_0, \quad u_0|_\Gamma = C^0. \quad (2.3)$$

Then  $\lim_{n \rightarrow \infty} K_0^n U_0(w) = 0$  and  $U_0(w) \geq C^0$ .

**Proof.** The first claim of the lemma follows from the representation

$$U_0(w) = \sum_{i=0}^n K_0^i H_0 + K_0^{n+1} U_0(w)$$

relating to the fact that, under the conditions of the lemma, the Neumann series converges (see the proof of Lemma 1) and satisfies the equation

$$U_0(r, 0) = \int_{S(r)} \frac{U_0(r'(s), 0)}{4\pi d^2(r)} ds + \frac{c_0 d^2}{18} \int_{D(r)} F_0[U_0(r', 0) + |U_0(r', 1)|] dr' + \frac{d^2 g_0}{6}.$$

On the other hand, the function  $u_0(r)$  in  $\Omega \setminus \Gamma_\varepsilon$  satisfies the equation

$$u_0(r) = \int_{S(r)} \frac{u_0(r'(s))}{4\pi d^2(r)} ds + \frac{c_0 d^2(r)}{18} \int_{D(r)} F_0 u_0(r') dr' + \frac{d^2 g_0}{6}.$$

Hence,

$$U_0(r, 0) \geq u_0(r) \geq C^0.$$

Using this estimate for  $U_0(r, 0)$  together with the integral equation for  $U_0(r, 1)$ , we obtain

$$U_0(r, 1) = \int_{S(r)} \frac{U_0 ds}{4\pi d^2} + \frac{c_0 d^2}{12} \int_{D(r)} F[U_0(r', 0) + |U_0(r', 1)|] dr' + \frac{d^2 g_0}{4} \geq C^0,$$

which completes the proof of the second claim of the lemma.  $\square$

**Theorem 1.** *Under the conditions of Lemma 1, there exists a unique bounded solution to (1.7) which is representable by the Neumann series; moreover,  $U_1(r, 0) = u(r)$ ,  $U_1(r, 1) = \frac{d(r)}{3} \frac{\partial u}{\partial l}(r)$ .*

**Proof.** Let  $u(r)$  be a solution such that

$$|u(r)| \leq C_1 \quad \text{and} \quad \left| \frac{d(r)}{3} \frac{\partial u}{\partial l} \right| \leq C_1.$$

Then

$$U_1 = \sum_{i=0}^n K^i H + K^{n+1} U_1, \quad |K^{n+1} U_1| \leq \frac{C_1}{C_0} K^{n+1} U_0.$$

This yields a representation for  $U_1$  in the form of a Neumann series. The remaining assertions of the theorem are valid in view of uniqueness of a bounded solution to the original differential problem.  $\square$

**Remark.** To estimate the derivative of a solution  $u$  in an arbitrary direction  $\mu$  (rather than only in the direction of the velocity  $v$ ), at the first step of the algorithm we should use for  $\frac{d(r)}{3} \frac{\partial u}{\partial \mu}$  a representation similar to (1.5):

$$\begin{aligned} \frac{d(r)}{3} \frac{\partial u}{\partial \mu}(r) = h_\mu(r) + \left[ 1 - \frac{c_0 d^2(r)}{6} \right] \int_{S(r)} \frac{a_\mu u(r'(s))}{1 - c_0 d^2/6} \frac{ds}{4\pi d^2(r)} + \\ \left[ \frac{c_0 d^2(r)}{6} \right] \int_{D(r)} \left( \frac{3a_\mu c(r')}{2c_0} u(r') + \frac{3a_\mu v(r')}{2c_0} \frac{\partial u}{\partial l}(r') \right) F(r, r') dr'. \end{aligned} \quad (2.4)$$

After the above-described randomization of representation (2.4), we implement the modeling algorithm that relates to the basis vector  $l(r)$ .

Since the values  $U(w)$  are unknown in  $\Gamma_\varepsilon$ , we construct estimators for these values as follows. For  $j_N = 0$  we can put  $H(r_N, 0) = u(r_N) = \psi(r_N^*)$ , where

$$r_N^* \in \Gamma, \quad r_N \in \Gamma_\varepsilon, \quad |r_N - r_N^*| = d(r_N).$$

Assume that the first-order derivatives of a solution are bounded in  $\Omega$ , i.e.,

$$\frac{d(r)}{3} \frac{\partial u}{\partial l} = O(\varepsilon) \quad \text{for } r \in \Gamma_\varepsilon.$$

Then for  $j_N = 1$  we can take approximately  $H(r_N, j_N) = 0$ . As a result, we obtain a biased estimator  $\xi_\varepsilon(w_0)$  for a solution.

**Theorem 2.** *Suppose that the first-order derivatives of the function  $u(r)$  are bounded in  $\Omega$  and that the conditions of Lemma 1 are satisfied. Then  $E\xi_\varepsilon(r, 0) = u_\varepsilon(r)$  exists, and*

$$|u(r) - u_\varepsilon(r)| \leq C_2\varepsilon, \quad \varepsilon > 0, \quad r \in \Omega.$$

Moreover,  $E\xi_\varepsilon(r, 1) = f_{l\varepsilon}(r)$  exists, and

$$\left| \frac{d(r)}{3} \frac{\partial u}{\partial l} - f_{l\varepsilon}(r) \right| \leq C_3\varepsilon, \quad \varepsilon > 0, \quad r \in \Omega.$$

**Proof.** Obviously,

$$|\xi - \xi_\varepsilon| = |Q_N[U(r_N, j) - \psi(r_N^*)(1 - j)]| \leq Q_N^{(0)}\varepsilon C_4,$$

where  $Q_N^{(0)}$  is the weight corresponding to some standard estimator of a walk on spheres for the case  $c < c^*$ ,  $g \equiv 0$ .  $\square$

**Theorem 3.** *Suppose that (2.8) is satisfied,  $c_0 \leq 0.488c^*$ , and  $g \equiv 0$ . Then  $D\xi_\varepsilon < C_d < +\infty$  for all  $\varepsilon > 0$ .*

**Proof.** Put  $y = c_0/c^*$ ,  $t = d\sqrt{c^*}$ . Direct calculations show that the value

$$\max \left\{ y > 0 : \left( \frac{1}{1 - yt^2/6} \right)^2 \leq \frac{t}{\sin t} \right\}$$

is attained at a point  $y^*$  such that  $0.488 < y^* < 0.489$ ; moreover, the value of  $\frac{t}{\sin t}(1 - yt^2/6)^2$  is minimal and equal to unity for  $t \approx 2.175$ . Hence,  $\xi_\varepsilon^2$  is dominated in the same way as  $\xi$  in the proof of Lemma 1.  $\square$

To relax the boundedness condition on variance, we carry out the following modification of the estimator. We calculate the function  $H(r, j)$  only at the step  $(r, j) \rightarrow (r', 0)$ , i.e., at the step to a sphere, but with the weight  $[1 - c_0 d^2(r)/6]^{-1}$ . Thus,  $H(r, j) \rightarrow \tilde{H}(r, j)$ :

$$\tilde{H}(r_{k_i-1}, j) = 0, \quad \tilde{H}(r_{t_i-1}, j) = \frac{1}{1 - c_0 d^2(r_{t_i-1})/6} H(r_{t_i-1}, j).$$

In the place of the estimator  $\xi_\varepsilon$ , we thereby consider the estimator  $\xi_{\varepsilon,1}$  for which  $E \xi_\varepsilon = E \xi_{\varepsilon,1}$ .

**Theorem 4.** *Under the conditions of Theorem 3 the following estimates hold for  $g \neq 0$ :  $D \xi_{\varepsilon,1} < C_{d,1} < +\infty$  for all  $\varepsilon > 0$ .*

**Proof.** Assuming the conditions of the theorem, we have

$$\frac{d\sqrt{c^*}}{\sin(d\sqrt{c^*})} - 1 > \left( \frac{1}{1 - c_0 d^2/6} \right)^2 - 1 \geq C_5 d^2.$$

Also, observe that  $H(r, j) = O(d^2(r))$ . Put  $s(c, d) = \frac{d\sqrt{c}}{\sin(d\sqrt{c})}$ . Termwise dominating  $|\xi_{\varepsilon,1}|$  by the standard estimator  $\eta^{(0)}$  of a "walk on spheres" for the case  $c \equiv c_0/3 < 0.488c^*/3$  with the replacement  $H \rightarrow \tilde{H}$ ,  $3c/c_0 \rightarrow 1$ ,  $a(w, w') \rightarrow 1$ , we have

$$\begin{aligned} |\xi_{\varepsilon,1}| &\leq \sum_{n=0}^N |Q_n| |\tilde{H}(w_n)| \leq C_6 \sum_{i=0}^{N-m_N} \tilde{Q}_i d_i^2 \\ &\leq \frac{C_6}{C_5} \sum_{i=0}^{N-m_N} \left[ \prod_{j=0}^{i-1} s(c, d_j) \right] (s(c, d_i) - 1) \\ &= \frac{C_6}{C_5} \sum_{i=1}^{N-m_N} (\tilde{Q}_i - \tilde{Q}_{i-1}) = C_7 (Q_N^{(0)} - 1), \end{aligned} \quad (2.5)$$

Hence,  $|\xi_{\varepsilon,1}| \leq \eta^{(0)}$  for all  $\varepsilon > 0$ ; moreover  $D \eta^{(0)} < +\infty$ .  $\square$

## References

- [1] Ermakov S.M., Mikhailov G.A. Statistic Modeling. – Moscow: Nauka, 1982 (in Russian).
- [2] Mikhailov G.A. New Monte Carlo methods for solving the Helmholtz equation // Dokl. Akad. Nauk. – 1992. – Vol. 326, № 6. – P. 943–947.