

Concentrated force in a porous half-space*

Kh.Kh. Imomnazarov

The formulas for calculation the displacement of an elastic porous body, strains and pressure for simple forces using the Galerkin vector are obtained.

In [1] R. Mindlin and D. Cheng considered in an elastic half-space a problem of a concentrated force. They obtained the formulas for calculation the displacements and pressure for various simple forces using the Galerkin vector.

The similar problem for porous half-space is considered in the given work: to calculate a displacement of an elastic porous body, strains and pressure for simple forces. Thus the surface $z = 0$ is considered free from strains and pressure.

The equations of motions in a porous medium are obtained in terms of displacements [2], and in terms of velocities of displacements [3, 4]. Thus the Biot model contains four elastic constants. As was shown in [4, 5], the equations of motions of a porous medium contain three elastic constants.

We consider a boundary value problem in a porous half-space $z > 0$:

$$\mathbf{N}\Delta\mathbf{U} + (\mathbf{D} + \mathbf{N})\nabla \operatorname{div} \mathbf{U} + \mathbf{Q}\nabla \operatorname{div} \mathbf{V} + \rho_{0,s}\mathbf{f} = 0, \quad (1)$$

$$\mathbf{Q}\nabla \operatorname{div} \mathbf{U} + \mathbf{R}\nabla \operatorname{div} \mathbf{V} + \rho_{0,l}\mathbf{f} = 0, \quad (2)$$

$$\sigma_{xz}|_{z=0} = \sigma_{yz}|_{z=0} = \sigma_{zz}|_{z=0} = \frac{\rho_{0,l}}{\rho_0}P|_{z=0} = 0, \quad (3)$$

where \mathbf{Q} , \mathbf{R} , \mathbf{N} , \mathbf{D} are the elastic constants of the Biot theory, \mathbf{U} and \mathbf{V} are the vectors of displacements of an elastic porous body and fluids with partial densities $\rho_{0,s}$ and $\rho_{0,l}$ correspondingly, σ_{jz} is a strain tensor, $j = x, y, z$, P is a pressure, \mathbf{f} is a mass force, $\rho_0 = \rho_{0,s} + \rho_{0,l}$.

After differentiating on time system (4.2) from [2] and comparing with system (7.4), (7.5) from [5], we obtain the expression for the coefficients \mathbf{Q} , \mathbf{R} , \mathbf{N} , \mathbf{D} .

Then the system of equations (1), (2) has the following form:

$$\mu\Delta\mathbf{U} + \left(\lambda + \mu + \alpha\rho_{0,s}^2 - 2K\frac{\rho_{0,s}}{\rho_0} \right) \nabla \operatorname{div} \mathbf{U} - \rho_{0,l}(K/\rho_0 - \rho_{0,s}\alpha)\nabla \operatorname{div} \mathbf{V} + \rho_{0,s}\mathbf{f} = 0, \quad (4)$$

*Partially supported by the Russian Foundation for Basic Research under Grant 99-05-64538.

$$-\rho_{0,l}(K/\rho_0 - \rho_{0,s}\alpha)\nabla \operatorname{div} \mathbf{U} + \rho_{0,l}^2\alpha\nabla \operatorname{div} \mathbf{V} + \rho_{0,l}\mathbf{f} = 0. \quad (5)$$

Here $\lambda, \mu, \alpha = \rho_0\alpha_3 + K/\rho_0^2$ are the constants from the equation of state [5], $K = \lambda + 2\mu/3$.

We consider a porous medium, i.e., $\rho_{0,l} > 0$.

Let us exclude $\nabla \operatorname{div} \mathbf{V}$ from (4). Using equation (5), we obtain

$$\mu\Delta\mathbf{U} + (\tilde{\lambda} + \mu)\nabla \operatorname{div} \mathbf{U} + (\alpha\rho_0)^{-1}K\mathbf{f} = 0, \quad (6)$$

where $\tilde{\lambda} = \lambda - (\rho_0^2\alpha)^{-1}K^2$.

From boundary conditions (3) we exclude $\operatorname{div} \mathbf{V}$, then using the definitions of a tensor strains and pressure, we obtain

$$\begin{aligned} \mu \left(\frac{\partial U_x}{\partial z} + \frac{\partial U_z}{\partial x} \right) \Big|_{z=0} = 0, \quad \mu \left(\frac{\partial U_y}{\partial z} + \frac{\partial U_z}{\partial y} \right) \Big|_{z=0} = 0, \\ 2\mu \frac{\partial U_z}{\partial z} + \tilde{\lambda} \operatorname{div} \mathbf{U} \Big|_{z=0} = 0. \end{aligned} \quad (7)$$

Now we exclude a mass force \mathbf{f} from equation (5) and using equation (4), we obtain $\operatorname{div} \mathbf{V}$ from the equation

$$\nabla \operatorname{div} \mathbf{V} = \frac{\rho_0}{\rho_{0,l}} \frac{\mu}{K} \Delta \mathbf{U} + \left(\frac{\lambda + \mu}{K} \frac{\rho_0}{\rho_{0,l}} - \frac{\rho_{0,s}}{\rho_{0,l}} \right) \nabla \operatorname{div} \mathbf{U} \quad (8)$$

with a boundary condition

$$\operatorname{div} \mathbf{V} \Big|_{z=0} = (\alpha\rho_{0,l})^{-1} (K/\rho_0 - \rho_{0,s}\alpha) \operatorname{div} \mathbf{U} \Big|_{z=0}. \quad (9)$$

Thus, boundary value problem (1)–(3) was divided in two sequentially solvable problems. With the help of a Galerkin vector $\mathbf{F} = iX + jY + kZ$, we find the vector of displacements and strains by the following formulas [1]:

$$\begin{aligned} U_x &= \frac{1}{2\mu} \left[2(1 - \nu)\Delta X - \frac{\partial}{\partial x} \operatorname{div} \mathbf{F} \right], \\ \sigma_{xx} &= 2(1 - \nu) \frac{\partial}{\partial x} \Delta X + \left(\nu\Delta - \frac{\partial^2}{\partial x^2} \right) \operatorname{div} \mathbf{F}, \\ U_y &= \frac{1}{2\mu} \left[2(1 - \nu)\Delta Y - \frac{\partial}{\partial y} \operatorname{div} \mathbf{F} \right], \\ \sigma_{yy} &= 2(1 - \nu) \frac{\partial}{\partial y} \Delta Y + \left(\nu\Delta - \frac{\partial^2}{\partial y^2} \right) \operatorname{div} \mathbf{F}, \\ U_z &= \frac{1}{2\mu} \left[2(1 - \nu)\Delta Z - \frac{\partial}{\partial z} \operatorname{div} \mathbf{F} \right], \\ \sigma_{zz} &= 2(1 - \nu) \frac{\partial}{\partial z} \Delta Z + \left(\nu\Delta - \frac{\partial^2}{\partial z^2} \right) \operatorname{div} \mathbf{F}, \end{aligned}$$

$$\begin{aligned}\sigma_{xy} &= (1 - \tilde{\nu}) \left(\frac{\partial}{\partial y} \Delta X + \frac{\partial}{\partial x} \Delta Y \right) - \frac{\partial^2}{\partial x \partial y} \operatorname{div} \mathbf{F}, \\ \sigma_{xz} &= (1 - \tilde{\nu}) \left(\frac{\partial}{\partial x} \Delta Z + \frac{\partial}{\partial z} \Delta X \right) - \frac{\partial^2}{\partial x \partial z} \operatorname{div} \mathbf{F}, \\ \sigma_{yz} &= (1 - \tilde{\nu}) \left(\frac{\partial}{\partial z} \Delta Y + \frac{\partial}{\partial y} \Delta Z \right) - \frac{\partial^2}{\partial y \partial z} \operatorname{div} \mathbf{F}, \\ \Delta^2 \mathbf{F} &= \frac{1}{\tilde{\nu} - 1} (\alpha \rho_0)^{-1} K \mathbf{f}.\end{aligned}$$

Here i, j, k are the unit vectors of an orthogonal system, $\tilde{\nu} = \tilde{\lambda}/[2(\tilde{\lambda} + \mu)]$. We note that $\tilde{\nu}$ has a sign.

Solving the boundary value problem (8), (9) we obtain the expressions for the pressure

$$\begin{aligned}P &= \left(K - \frac{\lambda + \mu}{K} \rho_0^2 \alpha \right) \operatorname{div} \mathbf{U} - \left(K - \frac{\lambda + \mu + 0.5\tilde{\lambda}}{K} \rho_0^2 \alpha \right) \operatorname{div} \mathbf{U}|_{z=0} - \\ &\quad \frac{\mu}{K} \rho_0^2 \alpha \left(\left(\frac{\partial^2}{\partial x^2} + \frac{\partial^2}{\partial y^2} \right) \int_0^z U_3(x, y, \xi) d\xi + \frac{\partial U_3}{\partial z} \right).\end{aligned}$$

References

- [1] Mindlin R., Cheng D. Concentrated force in an elastic half-space // *J. Appl. Phys.* - 1950. - Vol. 21, № 9. - P. 118-133.
- [2] Biot M.A. Theory of propagation of elastic waves in a fluid-saturated porous solid // *J. Acoust. Soc. Amer.* - 1956. - Vol. 28, № 2. - P. 168-191.
- [3] Dorovsky V.N. Continual theory of filtration // *Sov. Geology and Geophysics.* - 1989. - Vol. 30, № 7. - P. 34-39.
- [4] Dorovsky V.N., Perepechko Yu.V., Romensky E.I. Wave processes in saturated porous elastically deformed media // *Combustion, Explosion and Shock Waves.* - 1993. - Vol. 29, № 1. - P. 93-103.
- [5] Blokhin A.M., Dorovsky V.N. *Mathematical Modelling in the Theory of Multivelocity Continuum.* - Nova Science, 1995.