

Studying tsunami waves propagation above the parabolic bottom topography within the wave-ray approximation

An.G. Marchuk

Abstract. In this paper, the kinematics of the tsunami wave ray and the wave front in the area, where the depth increases proportional to the squared distance to the straight shoreline, is studied. The exact analytical solution for the wave-ray trajectory above the parabolic bottom topography has been derived. This solution gives the possibility to determine in the ray approximation the tsunami wave heights in an area with the parabolic bottom topography. The distribution of the wave-height maxima in the area with such a bathymetry is compared to that obtained with a shallow-water model.

Keywords: tsunami propagation, shallow-water equations, wave ray, wave front kinematics.

1. Some features of the long wave propagation

Tsunami waves, usually generated by vertical displacements of large ocean bottom areas, belong to a class of long waves whose length is at least ten times greater than the depth. The propagation of such waves in a deep ocean, where the wave height is usually two orders lower than the depth, is described by a linear system of differential shallow-water equations [1]. The validity of this description has many times been verified in practice. In the one-dimensional case without external forces (except for the gravity) these equations can be written down in the following form:

$$\frac{\partial u}{\partial t} + g \frac{\partial \eta}{\partial x} = 0, \quad \frac{\partial \eta}{\partial t} + \frac{\partial(Du)}{\partial x} = 0.$$

Here u is the horizontal water flow velocity in the wave, η is the water surface height above an unperturbed level, g is the acceleration of gravity, and D is the depth. It follows from the shallow-water equations that the wave velocity does not depend on its length and is determined by the Lagrange formula [1]:

$$c = \sqrt{gD}. \quad (1)$$

This formula is of fundamental importance for the kinematics of long waves (in particular, tsunamis). For the description the tsunami wave dynamics in the coastal zone, where the tsunami amplitude increases and

the depth decreases, the nonlinear shallow water model is used [2]. The wave propagation velocity for this model is expressed by the formula $c = \sqrt{g(D + \eta)}$.

For the linear system of shallow water equations the horizontal flow velocity in a moving wave has the form [3]:

$$u = \eta \sqrt{\frac{g}{D}}, \quad (2)$$

and for the nonlinear tsunami wave formula (2) will be changed to

$$u = \eta \sqrt{\frac{g}{D + \eta}}.$$

Independence of the tsunami front propagation velocity on the wave parameters (height and length) gives the possibility for a priori discovery of peculiarities of the wave behavior in areas with uneven bottom. In the paper [3], the formula for the surface evaluation varying in the moving wave has been derived. In the linear case, it can be written down as

$$\eta_2(x) \approx \eta_1(x) \sqrt[4]{\frac{D_1}{D_2}}, \quad (3)$$

where η_2 and D_2 are the current wave elevation and depth and η_1 and D_1 are the initial values. It is the well-known Green formula describing a height variation of a long wave over an uneven bottom in the one-dimensional case. If a wave front is not straight, the wave amplitude varies not only due to the non-constant depth, but also as a result of wave refraction, that is, the wave-front line transformation. In the same paper [3] the relation between the wave segment length and the amplitude of this wave segment was also obtained

$$\eta_2 = \eta_1 \sqrt{\frac{L_1}{L_2}}. \quad (4)$$

Here L_2 is the current length of the wave segment and L_1 is its initial length.

Thus, due to the cylindrical propagation, the tsunami wave height decreases inversely proportional to the square root of the circular front radius or the wave front length. In general, the kinematics of propagation of perturbations in various media is described by the eikonal equation. The governing formulas for the wave-front kinematics are presented in [4], where the wave ray concept one of whose properties is the orthogonality to the wave-front line at any time is introduced. Along wave rays, a perturbation propagates from a source to other points of the medium in the least time. This means that wave rays are the fastest routes. Between the two closely spaced wave rays (in a ray tube), the wave energy remains constant [4]. Therefore, for a wave segment in a ray tube, formulas (3) and (4) can be rewritten in the form

$$\eta_2 = \eta_1 \sqrt{\frac{L_1}{L_2}} \sqrt[4]{\frac{D_1}{D_2}}, \quad (5)$$

where L_1 and L_2 are the widths of the ray tube (the length of the wave-front line segment inside the ray tube) at the initial and current time moments of wave propagation.

2. Exact analytical formulas for wave-ray traces above the parabolic bottom topography

An exact mathematical formula for a wave ray trajectory over a parabolic bottom can be found from the laws of geometrical optics. Let us consider a two-dimensional water area where the depth and the wave propagation velocity vary only in one direction. In this case we can use the Snell law for the wave ray refraction angle in a medium with varying optical conductivity [5]. According to this law, if in a two-dimensional conducting medium a ray comes at the angle of incidence α_1 to the horizontal line (Figure 1), where the conductivity (the propagation velocity of a signal) changes from b_1 to b_2 , then after passing the interface its direction α_2 changes according to the formula

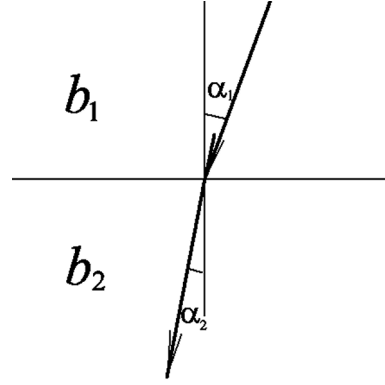


Figure 1. Refraction of a wave ray at the interface between two media

$$\frac{\sin \alpha_1}{b_1} = \frac{\sin \alpha_2}{b_2}.$$

Thus, in a medium where the conductivity b (the wave propagation velocity) varies only along one spatial variable (for instance, $b(y)$), the wave ray inclination from the direction of a change in the conductivity α changes according to the formula

$$\frac{\sin \alpha(y)}{b(y)} = \text{const} = \frac{\sin \alpha_0}{b(y_0)}. \quad (6)$$

Here α_0 is the initial incidence angle of the wave ray with respect to the vertical at the level $y = y_0$. In the case of a parabolic bottom, where the depth is proportional to the squared medium conductivity (the tsunami wave propagation velocity) can be determined by the Lagrange formula (1), which for a parabolic bottom has the following form:

$$a(y) = \sqrt{gb_1 y^2} = b_2 y. \quad (7)$$

Here g is the gravity acceleration, y is the distance to the straight coastline, where $y = 0$, b_1 and b_2 are constant in the whole area. In this case, the Snell law (6) gives the following relation between the offshore distance and wave-ray direction α according to the coastline normal

$$y(\alpha) = b_3 \sin \alpha, \quad (8)$$

where b_3 is also a constant.

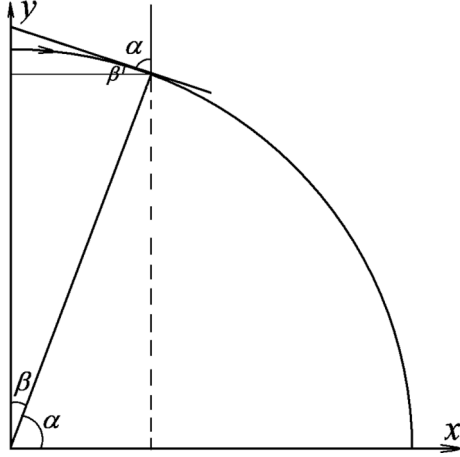


Figure 2. The wave ray refraction over the parabolic bottom topography

In order to determine the wave ray trajectory above such a bottom topography let us consider the following problem. Let the point $(0, y_0)$ be a starting point for the wave ray that exits this point in parallel to the shoreline direction (Figure 2). At the starting point, the angle $\alpha = \pi/2$. The inclination angle of a wave ray $y(x)$ to the X -axis will be expressed as $\beta = \pi/2 - \alpha$ (see Figure 2). Hence, we have

$$\frac{dy}{dx} = \operatorname{tg} \beta, \quad 0 < \beta < \pi/2, \quad \text{or}$$

$$dx = dy \frac{\cos \beta}{\sin \beta}. \quad (9)$$

From (8) and (9) follows

$$dx = b_3 \cos \beta d\beta.$$

Assuming that along the wave ray the angle β varies from zero to the positive value β_1 , then after conducting the integration we obtain

$$x = b_3 \sin \beta \Big|_0^{\beta_1} = b_3 \sin \beta_1 = b_3 \cos \alpha_1, \quad (10)$$

where $\alpha_1 = \pi/2 - \beta_1$. In addition to this, as follows from (8) for any value of α_1 from the interval $(0, \pi/2)$

$$y = b_3 \sin \alpha_1. \quad (11)$$

Formulas (10), (11) present the parametric equation of the circle of radius b_3 with a center located at the coordinate origin. This radius can be easily determined from (8). From this formula it also follows that the circle center is always situated on the X -axis. In the case when the initial wave-ray

outgoing direction was in parallel to the shoreline, the circle radius is equal to the offshore distance at this moment. If at some time instance the angle between the ray and the Y -axis is equal to α_0 and the offshore distance at this moment is equal to y_0 , then the radius of the circle which presents the wave ray can be found from (8):

$$r = b_3 = \frac{y_0}{\sin \alpha_0}.$$

If $\alpha_0 = 0$, but at the same time $y_0 > 0$, then the radius will be infinitely big and the ray trajectory will be presented by the straight line which is orthogonal to the coastline.

Unlike the case with a sloping bottom [3] here the boundary value problem for a wave ray can be solved without difficulty. Let us have two points (a source and a receiver) in the area with the parabolic bottom topography. Let the receiver be situated at the coastline in the coordinate origin $(0, 0)$, and the source coordinates be the following: $x = x_0$, $y = y_0$. Let, for definiteness, $0 < x_0 < y_0$, which means that a wave ray monotonically approaches the shore (Figure 3).

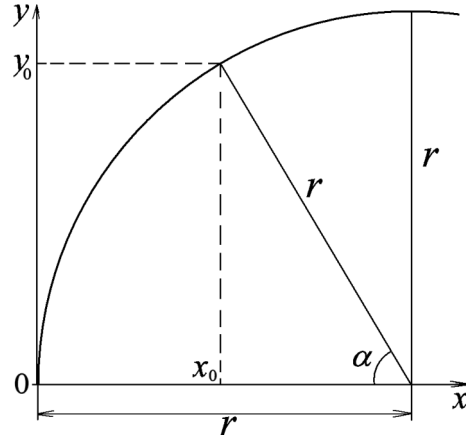


Figure 3. The scheme of solving the boundary-value problem for a wave ray above the parabolic bottom topography

Taking into account the fact that the wave ray is presented by the circle arc having the center at the shoreline ($y = 0$), the unknown radius r can easily be found from the equation of the circle passing the point (x_0, y_0) and the coordinate origin

$$(r - x_0)^2 + y_0^2 = r^2.$$

Resolving this equation for the variable r , the following expression will be written

$$r = \frac{x_0^2 + y_0^2}{2x_0}. \quad (12)$$

Then from the equation of a circle in parametric form $(r - x)^2 + y^2 = r^2$, the equation of the wave ray passing the point (x_0, y_0) and the coordinate origin can be written down as

$$y = \sqrt{x(2r - x)},$$

where the circle radius r is determined by formula (12).

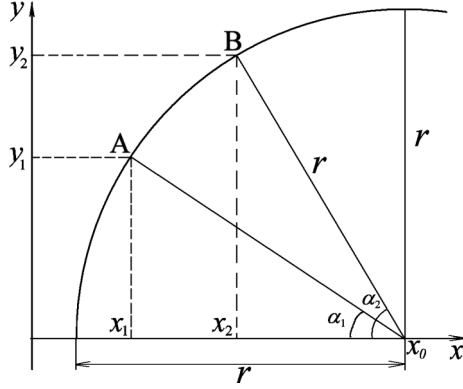


Figure 4. The scheme of the travel-time calculation along the wave ray between the points **A** and **B**

Now with the help of the previously derived formulas let us define the tsunami travel time along the wave ray. Let us consider the wave ray presenting an arc of the circle of radius r with the center located at the point $(x_0, 0)$ (Figure 4). Let initially (when $t = 0$) the wave front cross this wave ray at a point **A** with the coordinates (x_1, y_1) . In addition, the segment which connects the point **A** with the center of the circle is inclined at the angle α_1 to the X -axis (see Figure 4).

Let us find a travel time T which is required for the tsunami wave to arrive at the point **B** with the coordinates (x_2, y_2) and where the radius-vector inclination is equal to α_2 radians. If $0 < \alpha_1 < \alpha_2 \leq \pi$, then with allowance for (1) we can express the travel time as the Fermat integral

$$T = \int_{\alpha_1}^{\alpha_2} \frac{r d\alpha}{\sqrt{gD(x, y)}}. \quad (13)$$

The depth D all around the area varies according to the formula

$$D(x, y) = k^2 y^2. \quad (14)$$

When we come to the variable α , then (13) can be rewritten as

$$T = \frac{1}{\sqrt{g}} \int_{\alpha_1}^{\alpha_2} \frac{r d\alpha}{kr \sin \alpha} = \frac{1}{k_1} \ln \left| \operatorname{tg} \frac{\alpha}{2} \right| \Big|_{\alpha_1}^{\alpha_2} = \frac{1}{k_1} \left(\ln \left| \operatorname{tg} \frac{\alpha_2}{2} \right| - \ln \left| \operatorname{tg} \frac{\alpha_1}{2} \right| \right), \quad (15)$$

where $k_1 = k\sqrt{g}$. The angle α is counted clockwise from the X -axis. From (15) it is possible to express the angle α_2 through α_1 and T

$$\alpha_2 = 2 \operatorname{arctg} \left(\exp(k_1 T) \cdot \operatorname{tg} \frac{\alpha_1}{2} \right). \quad (16)$$

Finally, the coordinates of the destination point which the wave front will reach at the time T going along the wave ray, can be presented as

$$x_2(T, \alpha_1) = x_0 - r \cos \alpha_2, \quad y_2(T, \alpha_1) = r \sin \alpha_2. \quad (17)$$

Here α_2 is associated with T and α_1 according to (16). If $0 \leq \alpha_2 < \alpha_1 < \pi/2$, the expression for α_2 (16) will be as follows

$$\alpha_2 = 2 \operatorname{arctg} \left(\frac{\operatorname{tg} \frac{\alpha_1}{2}}{\exp(k_1 T)} \right). \quad (18)$$

The radius of this circle and its center position are uniquely determined from the source coordinates (x_1, y_1) and the exit angle of the wave ray α_1 (see Figure 4)

$$r = \frac{y_1}{\sin \alpha_1}, \quad x_0 = x_1 + r \cos \alpha_1 = x_1 + y_1 \operatorname{ctg} \alpha_1. \quad (19)$$

If $\alpha_1 = \pi/2$, the radius r is certainly equal to y_1 , and the abscises of the circle center is the same as the one for the ray exit point (i.e. x_1). Now, using formulas (16) and (18) it is easy to determine coordinates of the destination point (x_2, y_2) located on the ray, where the wave front arrives at the time instance T . The problem of determining the wave-rays in a medium with a linear propagation velocity distribution was studied earlier when studying seismic waves and the formulas for the wave ray trajectory in such a medium and for the wave travel-times were obtained [6, 7]. However, the parameterization of these formulas differs from the ones presented in this paper.

3. Determination of a wave-front line and estimation of the wave height above the parabolic bottom

For some model shapes of the bottom, distributions of wave amplitudes (heights) can be found analytically. Consider, for example, the coastal area where the depth increases with a squared distance to the coast with a model tsunami source in the form of a circle of radius R_0 with the center at a distance of y_{00} from a straight coastline. In Figure 5, this line coincides with the axis OX ($y = 0$). In Section 2, the wave ray trajectory over a parabolic bottom (as in the case in question) has already been found.

In order to determine a tsunami wave height all around the domain with the parabolic bottom topography, let us split it to many ray tubes varying the ray starting points and determining exiting angles there. Then using formulas (16) and (18) we can find coordinates of the points along each wave ray varying the time parameter T . The ray radius and the coordinate x of the circle center are given by (19).

If, for example, a tsunami source is presented by a circle of radius R_0 with its center located at the point (x_{00}, y_{00}) , then N wave rays start from the source boundary points in the radius-vector directions. Then we will obtain a set of N wave rays coming from the source boundary up to the edges of the computational domain. The scheme of constructing such a ray is shown in Figure 5. We will split the whole domain to N ray tubes by constructing wave rays exiting N different points which are equidistantly located around the source. Here it is necessary to take into account the

fact that coordinates of the ray starting points (x_i, y_i) vary according to the formulas

$$x_i = x_{00} + R_0 \sin \alpha_i, \quad y_i = y_{00} + R_0 \cos \alpha_i.$$

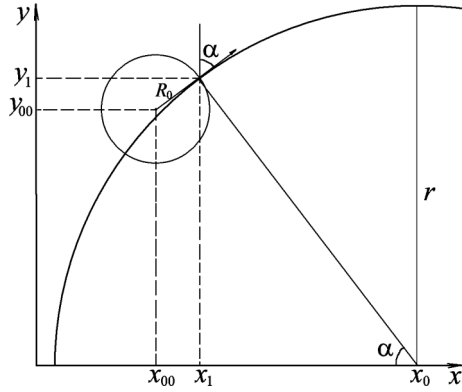


Figure 5. The wave-ray trace above the parabolic bottom which exits the circled source boundary point within the angle α relating to the ordinate axis

Here α_i is the ray exiting angle according to the ordinate axis. It is not allowed to say that rays reach the shoreline, because from (15) it follows that the required travel time for this is infinitely long.

Figure 6 shows the wave-ray set which was built using 200 ray exiting points along the circled source boundary. Their exiting angles α_i were equal to $i \cdot \pi/200$ ($i = 1, \dots, 200$). Thus, we have obtained the coordinates of the destination point versus the time T and the angle α . Now, with formulas (16) and (18) we can find the wave front location by fixing the time T .

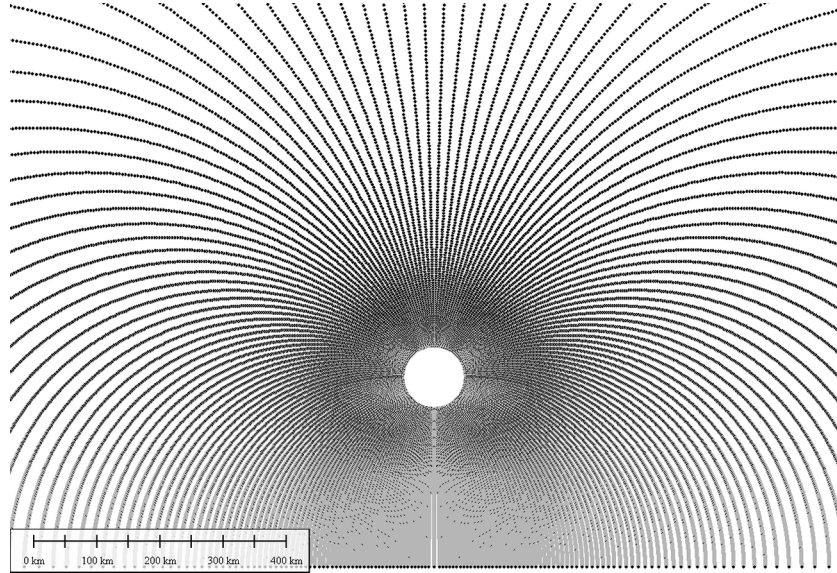


Figure 6. Wave-ray traces above the parabolic bottom topography coming from 200 points locating at the circled source boundary

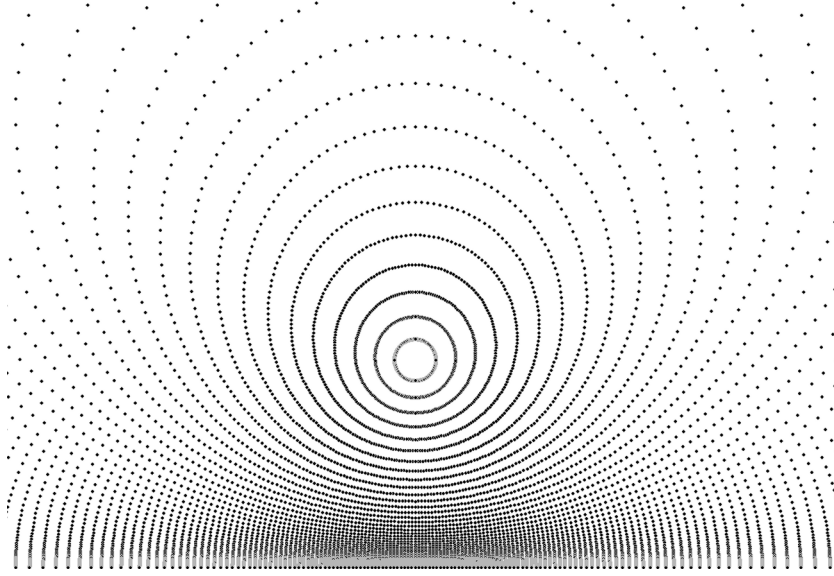


Figure 7. Positions of the tsunami wave front (isochrones) within the 5-minutes interval from a circled source of radius 50 km above the parabolic bottom topography

If we draw the lines connecting the points along wave rays corresponding to the same time instance, we will obtain tsunami isochrones. For example, Figure 7 shows locations of the wave front within 5-minutes interval. In this case, the center of the circled source of radius $R_0 = 50$ km was situated 300 km off the straight shoreline. Here the coefficient k of the parabolic depth growth (14) is equal to 10^{-4} . This means that at a distance of 1,000 km off the shore the depth is equal to 10,000 m.

If we want to estimate the wave height at the point (x_1, y_1) , it is necessary to determine the distance between the two following points: the first one is the point (x_1, y_1) , where the wave going along the ray exiting the point $(x_{00} + R_0 \sin \alpha, y_{00} + R_0 \cos \alpha)$ at the angle α (see Figure 5) arrives at the time T . The second one is the point (x_2, y_2) , where a tsunami wave arrives at the same time moment going along the wave ray exiting the point $(x_{00} + R_0 \sin(\alpha + \Delta\alpha), y_{00} + R_0 \cos(\alpha + \Delta\alpha))$ at the angle $\alpha + \Delta\alpha$. With formula (5), the coefficient of wave attenuation due to changing the ray tube width and depth is calculated. Doing this for various values of the time T and the directions of wave rays, we obtain the wave attenuation distribution over the entire area of points which can be reached by the wave rays from the initial wave front points.

To verify the solution obtained, the numerical simulation of the tsunami wave propagation was carried out using the differential shallow-water model with a software package called MOST [8]. In this numerical experiment the

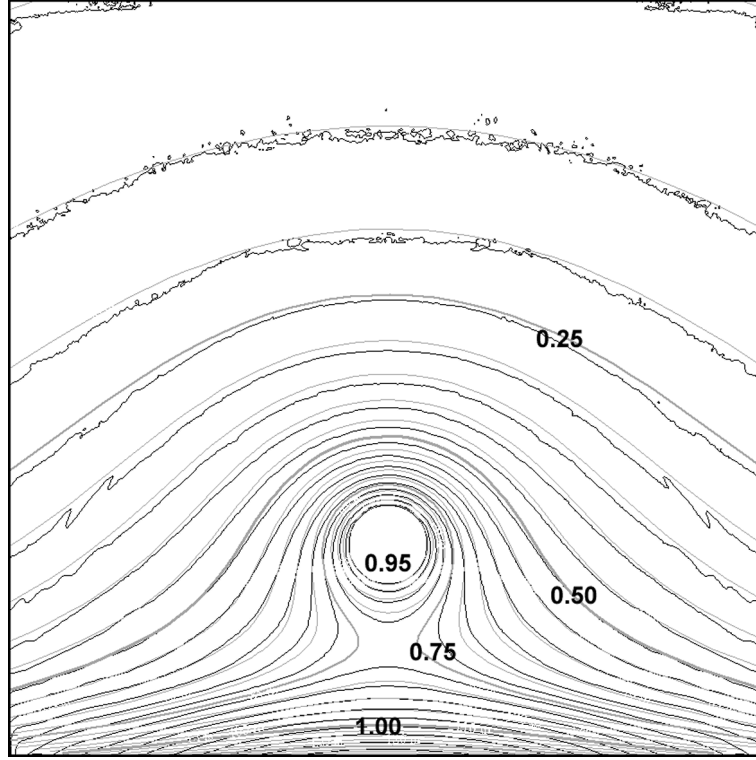


Figure 8. The comparative location of the wave-height maxima isolines obtained by numerical calculation of the shallow-water equations (black color) and within the wave-ray approximation (grey color)

center of a circular source, 40 km in radius, was located at a distance of 300 km from the coast. This source formed a 95-cm high circular wave at a distance of 50 km from the center. This initial front was taken as initial conditions to calculate the amplitudes with the ray model. In Figure 8, isolines of the tsunami wave height maxima in the 1000×1000 km coastal area with a parabolic bottom obtained from formulas (16)–(18) and (5) are shown by grey color. For comparison, isolines of the wave height maxima obtained by numerical solution of the same problem with the nonlinear shallow water model [8] having the same initial values are shown by black color. In both cases, the levels of isolines (whose height is shown in meters), were taken with a spacing of 5 cm. Figure 8 shows that the distributions of amplitudes obtained by the two different methods mostly coincide except the shelf area, where a depth is less than 150–200 m where, in contrast to the ray approximation, in the numerical implementation of the differential shallow water model the influence of the nonlinearity is much stronger than in a deep sea.

4. Conclusion

The height of a propagating tsunami wave versus depth and refraction above an uneven bottom has been estimated using the differential shallow-water equations. The exact wave ray trajectory and the tsunami isochrones above the parabolic bottom have been found. A comparison of the results obtained by the ray method and with the shallow water model has been made. This comparison shows that with a numerical method based on the ray approximation not only the arrival times of tsunami waves at different points, but also the wave heights in a deep water can be estimated. These solutions for travel times and wave-ray traces can be used for testing the numerical methods carrying out the tsunami simulation.

References

- [1] Stocker J.J. Water Waves. The Mathematical Theory with Applications. — New York: Interscience Publishers, 1957.
- [2] Marchuk An.G., Chubarov L.B., Shokin Yu.I. Numerical Simulation of Tsunami Waves. — Novosibirsk: Nauka, 1983 (In Russian).
- [3] Marchuk An.G. Estimating tsunami wave height over a sloping bottom in the ray approximation // Numerical Analysis and Applications. — 2015. — Vol. 8, No. 4. — P. 304–313.
- [4] Romanov V.G. Inverse Problems of Mathematical Physics. — Netherlands: VSP, 1984.
- [5] Sabra A.I. Theories of Light from Descartes to Newton. — Cambridge: University Press, 1981 (cf. Pavlos Mihas, Use of History in Developing ideas of refraction, lenses and rainbow, p. 5, Demokritus University, Thrace, Greece.)
- [6] Tsetsokho V.A., Belonosova A.V., Belonosov A.S. Calculation formulas of linear geometrical spreading at ray tracing in a 3D block-inhomogeneous gradient medium // Siberian J. Num. Math. — 2009. — Vol. 12, No. 3. — P. 325–339.
- [7] Belonosov A.S. Calculation formulas for wave ray and ray divergence in rectangular coordinates. — Novosibirsk, 1982. — (Preprint / SO AN SSSR, VC; 396).
- [8] Titov V.V., Gonzalez F. Implementation and testing of the method of splitting tsunami (MOST). — Washington DC, 1997. — (Technical Memorandum / National Oceanic and Atmospheric Administration; ERL PMEL-112).

